

Clipping

Line Clipping
Polygon Clipping
Clipping in Three Dimensions
[Angel Ch. 7.1-7.7]

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The Graphics Pipeline, Revisited

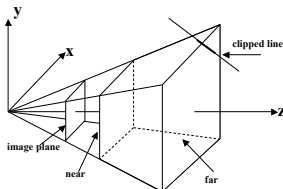


- Must eliminate objects that are outside of viewing frustum
- Clipping: object space (eye coordinates)
- Scissoring: image space (pixels in frame buffer)
 - most often less efficient than clipping
- We will first discuss 2D clipping (for simplicity)
 - OpenGL uses 3D clipping

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Clipping Against a Frustum

- General case of frustum (truncated pyramid)

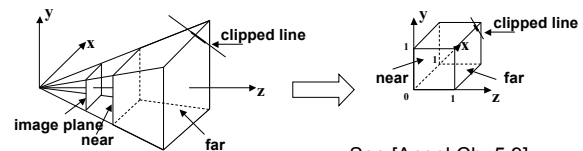


- Clipping is tricky because of frustum shape

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Perspective Normalization

- Solution:
 - Implement perspective projection by perspective normalization and orthographic projection
 - Perspective normalization is a homogeneous transformation



See [Angel Ch. 5.9]

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The Normalized Frustum

- OpenGL uses $-1 \leq x, y, z \leq 1$ (others possible)
- Clip against resulting cube
- Clipping against arbitrary (programmer-specified) planes requires more general algorithms and is more expensive

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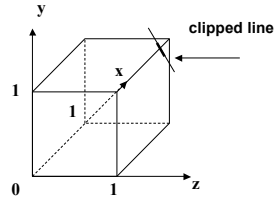
The Viewport Transformation

- Transformation sequence again:
 1. Camera: From object coordinates to eye coords
 2. Perspective normalization: to clip coordinates
 3. Clipping
 4. Perspective division: to normalized device coords.
 5. Orthographic projection (setting $z_p = 0$)
 6. Viewport transformation: to screen coordinates
- Viewport transformation can distort
 - Solution: pass the correct window aspect ratio to `gluPerspective`

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Clipping

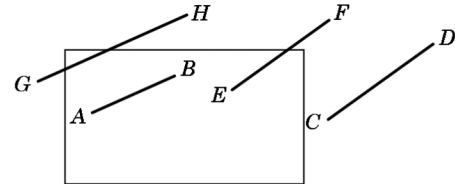
- General: 3D object against cube
- Simpler case:
 - In 2D: line against square or rectangle
 - Later: polygon clipping



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Clipping Against Rectangle in 2D

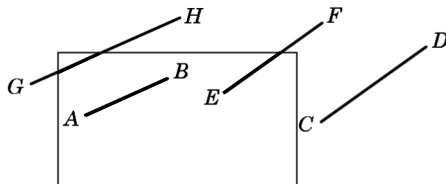
- Line-segment clipping: modify endpoints of lines to lie within clipping rectangle



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Clipping Against Rectangle in 2D

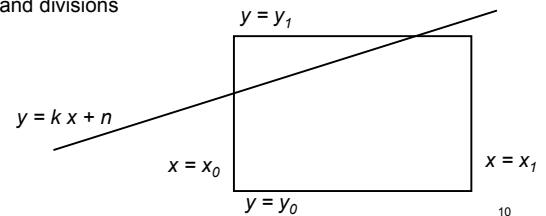
- The result (in red)



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Clipping Against Rectangle in 2D

- Could calculate intersections of line segments with clipping rectangle
 - expensive, due to floating point multiplications and divisions
- Want to minimize the number of multiplications and divisions



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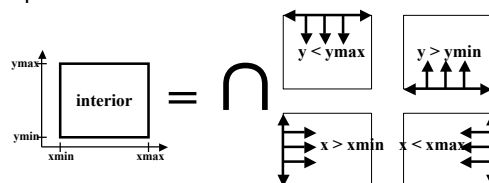
Several practical algorithms for clipping

- Main motivation:
 - Avoid expensive line-rectangle intersections (which require floating point divisions)
- Cohen-Sutherland Clipping
- Liang-Barsky Clipping
- There are many more (but many only work in 2D)

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Cohen-Sutherland Clipping

- Clipping rectangle is an intersection of 4 half-planes

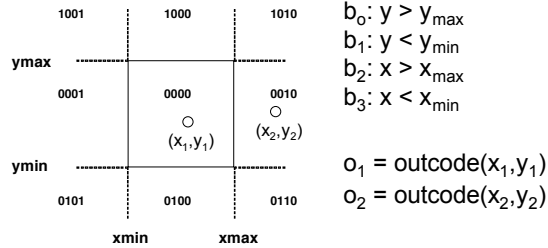


- Encode results of four half-plane tests
- Generalizes to 3 dimensions (6 half-planes)

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Outcodes (Cohen-Sutherland)

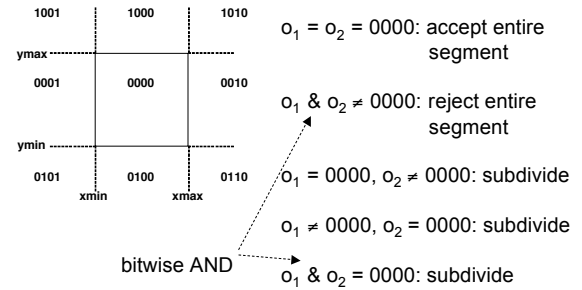
- Divide space into 9 regions
- 4-bit outcode determined by comparisons



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Cases for Outcodes

- Outcomes: accept, reject, subdivide



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Cohen-Sutherland Subdivision

- Pick outside endpoint ($o \neq 0000$)
- Pick a crossed edge ($o = b_0b_1b_2b_3$ and $b_k \neq 0$)
- Compute intersection of this line and this edge
- Replace endpoint with intersection point
- Restart with new line segment
 - Outcodes of second point are unchanged
- This algorithm converges

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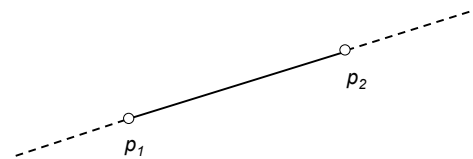
Liang-Barsky Clipping

- Start with parametric form for a line

$$p(\alpha) = (1 - \alpha)p_1 + \alpha p_2, \quad 0 \leq \alpha \leq 1$$

$$x(\alpha) = (1 - \alpha)x_1 + \alpha x_2$$

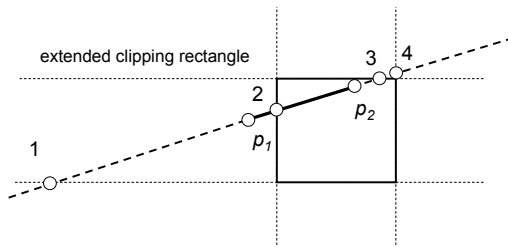
$$y(\alpha) = (1 - \alpha)y_1 + \alpha y_2$$



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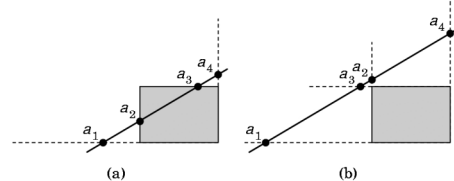
Liang-Barsky Clipping

- Compute all four intersections 1,2,3,4 with extended clipping rectangle
- Often, no need to compute all four intersections



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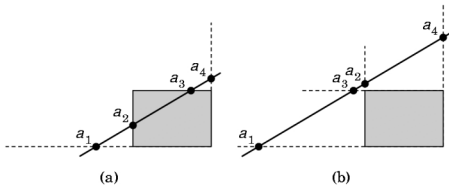
Ordering of intersection points



- Order the intersection points
- Figure (a): $1 > \alpha_4 > \alpha_3 > \alpha_2 > \alpha_1 > 0$
- Figure (b): $1 > \alpha_4 > \alpha_2 > \alpha_3 > \alpha_1 > 0$

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Liang-Barsky Idea



- It is possible to clip already if one knows the order of the four intersection points !
- Even if the actual intersections were not computed !
- Can enumerate all ordering cases

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Liang-Barsky efficiency improvements

- Efficiency improvement 1:
 - Compute intersections one by one
 - Often can reject before all four are computed
- Efficiency improvement 2:
 - Equations for α_3, α_2

$$y_{\max} = (1 - \alpha_3)y_1 + \alpha_3 y_2$$

$$x_{\min} = (1 - \alpha_2)x_1 + \alpha_2 x_2$$

$$\alpha_3 = \frac{y_{\max} - y_1}{y_2 - y_1} \quad \alpha_2 = \frac{x_{\min} - x_1}{x_2 - x_1}$$
 - Compare α_3, α_2 without floating-point division

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Line-Segment Clipping Assessment

- Cohen-Sutherland
 - Works well if many lines can be rejected early
 - Recursive structure (multiple subdivisions) is a drawback
- Liang-Barsky
 - Avoids recursive calls
 - Many cases to consider (tedious, but not expensive)

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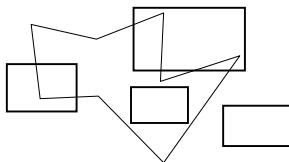
Outline

- Line-Segment Clipping
 - Cohen-Sutherland
 - Liang-Barsky
- Polygon Clipping
 - Sutherland-Hodgeman
- Clipping in Three Dimensions

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Polygon Clipping

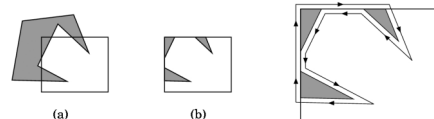
- Convert a polygon into one or more polygons
- Their union is intersection with clip window
- Alternatively, we can first tessellate concave polygons (OpenGL supported)



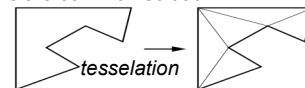
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Concave Polygons

- Approach 1: clip, and then join pieces to a single polygon
 - often difficult to manage



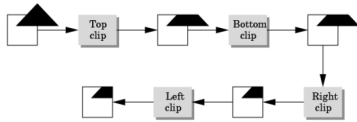
- Approach 2: tessellate and clip triangles
 - this is the common solution



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Sutherland-Hodgeman (part 1)

- Subproblem:
 - Input: polygon (vertex list) and single clip plane
 - Output: new (clipped) polygon (vertex list)
- Apply once for each clip plane
 - 4 in two dimensions
 - 6 in three dimensions
 - Can arrange in pipeline



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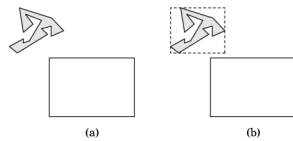
Sutherland-Hodgeman (part 2)

- To clip vertex list (polygon) against a half-plane:
 - Test first vertex. Output if inside, otherwise skip.
 - Then loop through list, testing transitions
 - In-to-in: output vertex
 - In-to-out: output intersection
 - out-to-in: output intersection and vertex
 - out-to-out: no output
 - Will output clipped polygon as vertex list
- May need some cleanup in concave case
- Can combine with Liang-Barsky idea

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Other Cases and Optimizations

- Curves and surfaces
 - Do it analytically if possible
 - Otherwise, approximate curves / surfaces by lines and polygons
- Bounding boxes
 - Easy to calculate and maintain
 - Sometimes big savings



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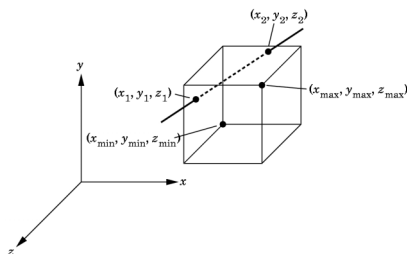
Outline

- Line-Segment Clipping
 - Cohen-Sutherland
 - Liang-Barsky
- Polygon Clipping
 - Sutherland-Hodgeman
- Clipping in Three Dimensions

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Clipping Against Cube

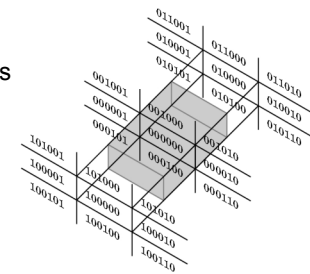
- Derived from earlier algorithms
- Can allow right parallelepiped



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Cohen-Sutherland in 3D

- Use 6 bits in outcode
 - $b_4: z > z_{max}$
 - $b_5: z < z_{min}$
- Other calculations as before



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Liang-Barsky in 3D

- Add equation $z(\alpha) = (1 - \alpha) z_1 + \alpha z_2$
- Solve, for p_0 in plane and normal \mathbf{n} :

$$p(\alpha) = (1 - \alpha)p_1 + \alpha p_2$$
$$\mathbf{n} \cdot (p(\alpha) - p_0) = 0$$

- Yields

$$\alpha = \frac{\mathbf{n} \cdot (p_0 - p_1)}{\mathbf{n} \cdot (p_2 - p_1)}$$

- Optimizations as for Liang-Barsky in 2D

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Summary: Clipping

- Clipping line segments to rectangle or cube
 - Avoid expensive multiplications and divisions
 - Cohen-Sutherland or Liang-Barsky
- Polygon clipping
 - Sutherland-Hodgeman pipeline
- Clipping in 3D
 - essentially extensions of 2D algorithms

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Preview and Announcements

- Scan conversion
- Anti-aliasing
- Other pixel-level operations
- Assignment 2 due a week from today!
- Assignment 1 video

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