CSCI 480 Computer Graphics Lecture 17

Spatial Data Structures

Hierarchical Bounding Volumes Regular Grids Octrees BSP Trees

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http://www-bcf.usc.edu/~jbarbic/cs480-s12/

Ray Tracing Acceleration

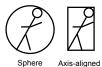
- · Faster intersections
 - Faster ray-object intersections
 - Object bounding volume
 - Efficient intersectors
 - Fewer ray-object intersections
 - · Hierarchical bounding volumes (boxes, spheres)
 - Spatial data structures
 - Directional techniques
- · Fewer rays
 - Adaptive tree-depth control
 - Stochastic sampling
- · Generalized rays (beams, cones)

Spatial Data Structures

- · Data structures to store geometric information
- · Sample applications
 - Collision detection
 - Location queries
 - Chemical simulations
 - Rendering
- · Spatial data structures for ray tracing
 - Object-centric data structures (bounding volumes)
 - Space subdivision (grids, octrees, BSP trees)
 - Speed-up of 10x, 100x, or more

Bounding Volumes

- · Wrap complex objects in simple ones
- · Does ray intersect bounding box?
 - No: does not intersect enclosed objects
 - Yes: calculate intersection with enclosed objects
- · Common types:





Box (AABB)



Oriented

Bounding

Box (OBB)



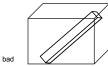


Convex Hull

Selection of Bounding Volumes

- · Effectiveness depends on:
 - Probability that ray hits bounding volume, but not enclosed objects (tight fit is better)
 - Expense to calculate intersections with bounding volume and enclosed objects
- Amortize calculation of bounding volumes
- · Use heuristics





Hierarchical Bounding Volumes

- · With simple bounding volumes, ray casting still requires O(n) intersection tests
- · Idea: use tree data structure
 - Larger bounding volumes contain smaller ones etc.
 - Sometimes naturally available (e.g. human figure)
 - Sometimes difficult to compute
- Often reduces complexity to O(log(n))







Ray Intersection Algorithm

- · Recursively descend tree
- · If ray misses bounding volume, no intersection
- If ray intersects bounding volume, recurse with enclosed volumes and objects
- · Maintain near and far bounds to prune further
- Overall effectiveness depends on model and constructed hierarchy

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Spatial Subdivision

- · Bounding volumes enclose objects, recursively
- Alternatively, divide space (as opposed to objects)
- For each segment of space, keep a list of intersecting surfaces or objects
- · Basic techniques:





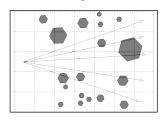


BSP-tree

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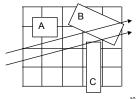
Grids

- 3D array of cells (voxels) that tile space
- · Each cell points to all intersecting surfaces
- Intersection algorithm steps from cell to cell



Caching Intersection points

- · Objects can span multiple cells
- · For A need to test intersection only once
- For B need to cache intersection and check next cell for any closer intersection with other objects
- If not, C could be missed (yellow ray)



Assessment of Grids

- · Poor choice when world is non-homogeneous
- · Size of grid
 - Too small: too many surfaces per cell
 - Too large: too many empty cells to traverse
 - Can use algorithms like Bresenham's for efficient traversal
- · Non-uniform spatial subdivision more flexible
 - Can adjust to objects that are present

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Outline

- · Hierarchical Bounding Volumes
- · Regular Grids
- Octrees
- BSP Trees

Quadtrees

- · Generalization of binary trees in 2D
 - Node (cell) is a square
 - Recursively split into 4 equal sub-squares
 - Stop subdivision based on number of objects
- · Ray intersection has to traverse quadtree
- · More difficult to step to next cell



Octrees

- · Generalization of quadtree in 3D
- Each cell may be split into 8 equal sub-cells
- · Internal nodes store pointers to children
- · Leaf nodes store list of surfaces
- · Adapts well to non-homogeneous scenes

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Assessment for Ray Tracing

- Grids
 - Easy to implement
 - Require a lot of memory
 - Poor results for non-homogeneous scenes
- Octrees
 - Better on most scenes (more adaptive)
- · Alternative: nested grids
- · Spatial subdivision expensive for animations
- · Hierarchical bounding volumes
 - Natural for hierarchical objects
 - Better for dynamic scenes

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Other Spatial Subdivision Techniques

- · Relax rules for quadtrees and octrees
- k-dimensional tree (k-d tree)
 - Split at arbitrary interior point
 - Split one dimension at a time
- · Binary space partitioning tree (BSP tree)
 - In 2 dimensions, split with any line
 - In k dims. split with k-1 dimensional hyperplane
 - Particularly useful for painter's algorithm
 - Can also be used for ray tracing

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Outline

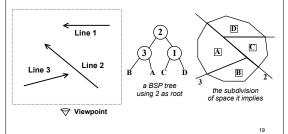
- · Hierarchical Bounding Volumes
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- · BSP Trees

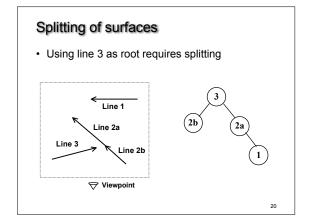
BSP Trees

- Split space with any line (2D) or plane (3D)
- Applications
 - Painters algorithm for hidden surface removal
 - Ray casting
- · Inherent spatial ordering given viewpoint
 - Left subtree: in front, right subtree: behind
- Problem: finding good space partitions
 - Proper ordering for any viewpoint
 - How to balance the tree

Building a BSP Tree

- · Use hidden surface removal as intuition
- · Using line 1 or line 2 as root is easy





Building a Good Tree

- Naive partitioning of n polygons yields O(n³) polygons (in 3D)
- · Algorithms with O(n2) increase exist
 - Try all, use polygon with fewest splits
 - Do not need to split exactly along polygon planes
- · Should balance tree
 - More splits allow easier balancing
 - Rebalancing?

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Painter's Algorithm with BSP Trees

- · Building the tree
 - May need to split some polygons
 - Slow, but done only once
- · Traverse back-to-front or front-to-back
 - Order is viewer-direction dependent
 - What is front and what is back of each line changes
 - Determine order on the fly

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Details of Painter's Algorithm

- Each face has form Ax + By + Cz + D
- · Plug in coordinates and determine
 - Positive: front side
 - Zero: on plane
 - Negative: back side
- · Back-to-front: inorder traversal, farther child first
- · Front-to-back: inorder traversal, near child first
- · Do backface culling with same sign test
- · Clip against visible portion of space (portals)

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Clipping With Spatial Data Structures Accelerate clipping Goal: accept or rejects whole sets of objects Can use an spatial data structures Scene should be mostly fixed Terrain fly-through viewing frustrum Gaming Hierarchical bounding volumes Octrees

Data Structure Demos

- BSP Tree construction http://symbolcraft.com/graphics/bsp/index.html
- KD Tree construction http://donar.umiacs.umd.edu/quadtree/points/kdtree.html

Real-Time and Interactive Ray Tracing

- Interactive ray tracing via space subdivision http://www.cs.utah.edu/~reinhard/egwr/
- State of the art in interactive ray tracing http://www.cs.utah.edu/~shirley/irt/

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Summary

- · Hierarchical Bounding Volumes
- Regular Grids
- Octrees
- BSP Trees